



APPLICATION OF MAGNETIC FORCE EXPORT PER TOOTH: VIBRATION ANALYSIS FOR ELECTRIC MOTORS AT MULTI-SPEED

FLUX 2D MULTIPHYSICS APPLICATION EXAMPLE

December 2020, Altair Valorization and Support Team

GENERAL PRESENTATION OUTLINE

Part 1: Introduction

Part 2: Motor pre-analysis in FluxMotor

Part 3: Magnetic force export in Flux

Part 4: Vibration analysis in SimLab

Part 5: Conclusion

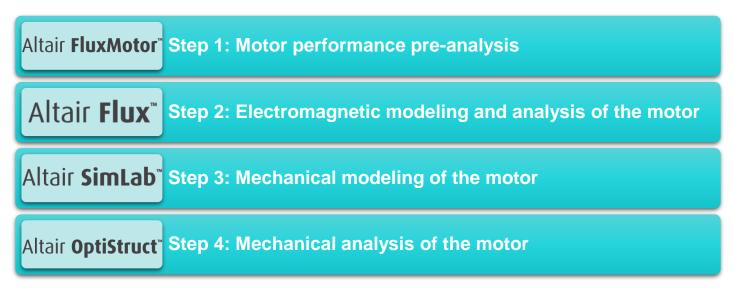


I. INTRODUCTION



INTRODUCTION

Electric motor vibration analysis at multi-speeds: solution with Altair HyperWorks

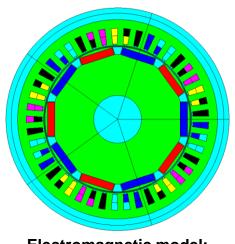


- Two excitation (magnetic forces) format are currently available from Flux to OptiStruct:
 - Magnetic force export via an imported mesh
 - Magnetic force export per tooth

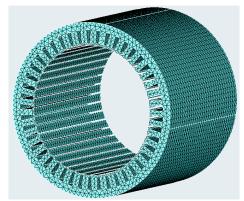


INTRODUCTION

- Tutorial example
 - The studied device is an inset permanent magnet synchronous motor (model: IkerMAQ).
 - The comprehensive magnetic and thermal analysis of the motor can be found in the Flux 2D supervisor example / Application notes / Magnetic and thermal analysis of a PMSM

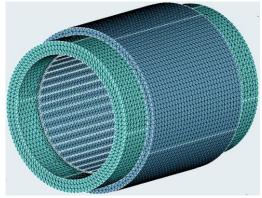


Electromagnetic model: Flux 2D project



a) Without windings

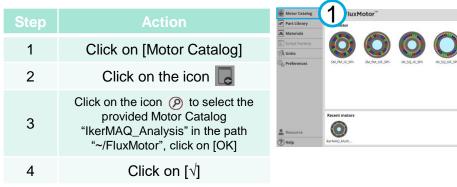
Mechanical model: SimLab projects



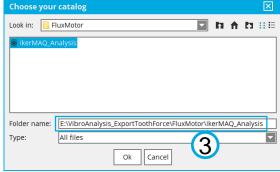
b) With windings 🛆 ALTAIR

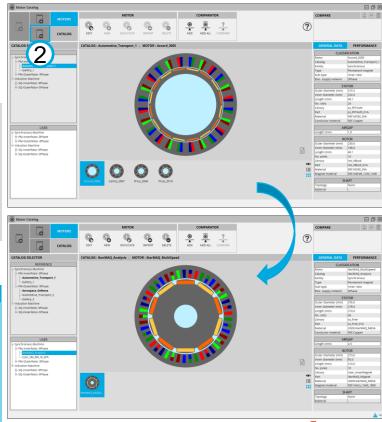


- FluxMotor project preparation
 - Import the Motor Catalog ("IkerMAQ_Analysis")





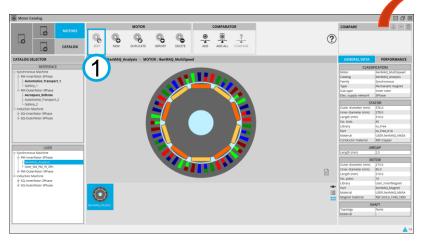


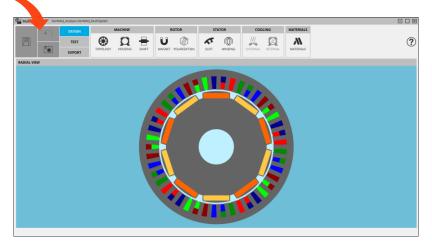




- Performance mapping test creation
 - Open "Motor Factory"



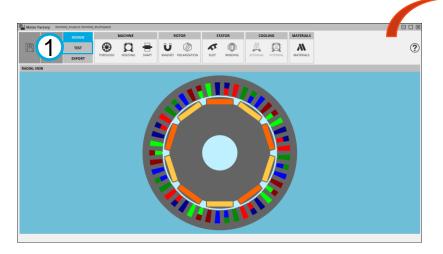


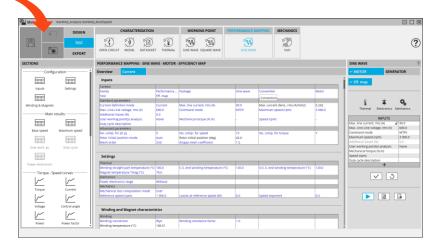




- Performance mapping test
 - Access the performance mapping test results

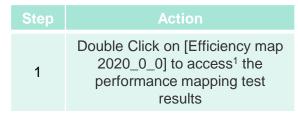
Step	Action
1	Click on [TEST] to enter the TEST editing interface
2	Click on the icon to access the sinewave test results

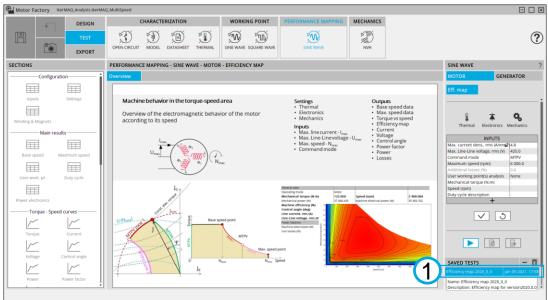






- Performance mapping test
 - Access the performance mapping test results

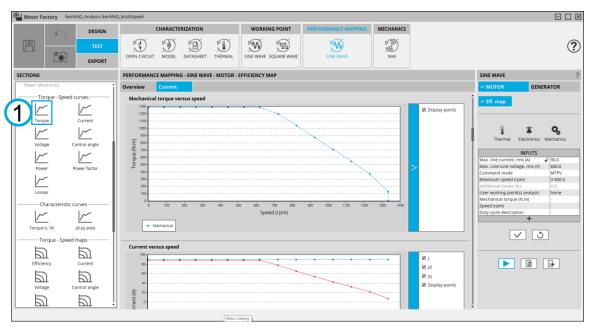






- Motor pre-analysis: sine wave
 - Mechanical torque results

Step	Action
1	In "SECTIONS", click on [Torque] in [Torque - Speed curves] to plot the torque speed curve.





- Motor pre-analysis: sine wave
 - Current results

Step	Action
1	In "SECTIONS", click on [Current] in [Current - Speed curves] to plot the current - speed curve.
2	Select serval working points for the analysis

Current / A	Speed / RPM
90.0	88.597
90.0	265.792
90.0	442.986
90.0	620.181
90.0	824.113
90.0	1028.046
90.0	1231.978





- Motor pre-analysis: sine wave
 - Control angle results

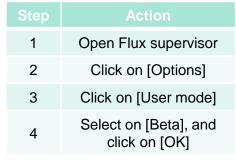
Step	Action
1	In "SECTIONS", click on [Control angle] in [Control angle - Speed curves] to plot the control angle-speed curve.
2	Select serval working points for the analysis

Control angle / deg	Speed / RPM
10.64	88.597
10.64	265.792
10.642	442.986
10.67	620.181
43.425	824.113
61.758	1028.046
76.19	1231.978





- Flux 2D project: initiation
 - Activate [Beta] mode (to access the menu for exporting global force)



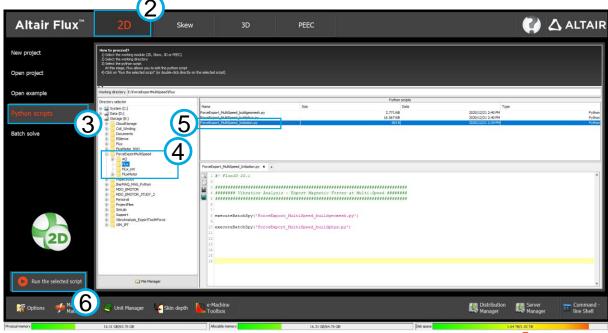




Flux 2D project: initiation

Load the physics-defined¹ Flux 2D project (driven by python script)

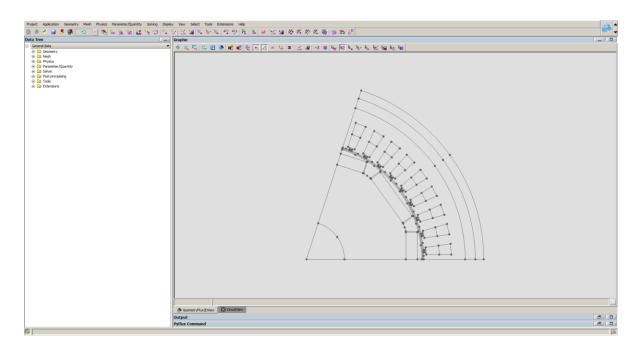
Step	Action
1	Open Flux supervisor
2	Select the [2D] simulation context
3	Click on [Python scripts]
4	Select the working path : "~/ForceExportMultiSpeed /Flux"
5	Select the python file "ForceExport_MultiSpeed_ Initiation.py"
6	Click on [Run the selected script]





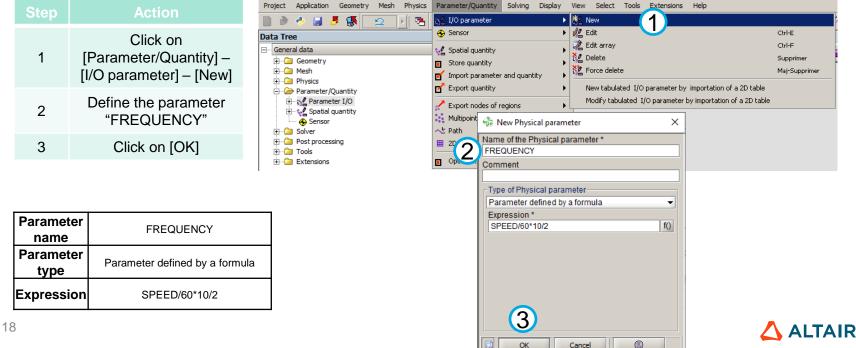


- Flux 2D project: initiation
 - Load the physics-defined Flux 2D project (driven by python script)

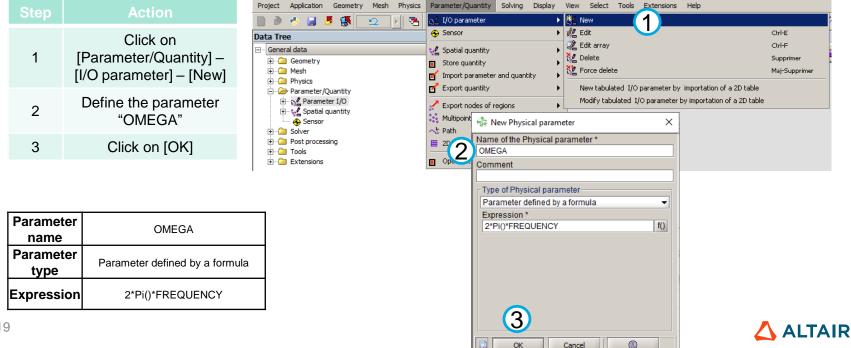




- Flux 2D project: physics modification
 - Create physics parameters: FREQUENCY



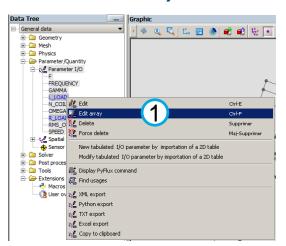
- Flux 2D project: physics modification
 - Create physics parameters: OMEGA

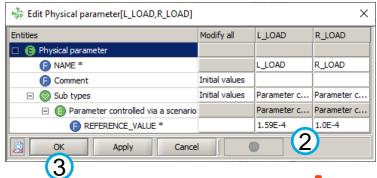


- Flux 2D project: physics modification
 - Modify physics parameters: L_LOAD + R_LOAD

Step	Action
1	Select from the Data Tree the two parameters "L_LOAD" and "R_LOAD", right click and click on [Edit array]
2	Modify the values of the two parameters
3	Click on [OK]

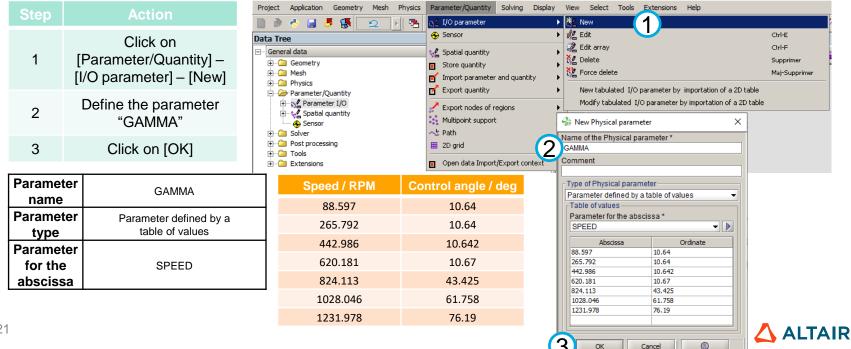
Parameter name	Value
L_LOAD	1.59E-4
R_LOAD	1.0E-4



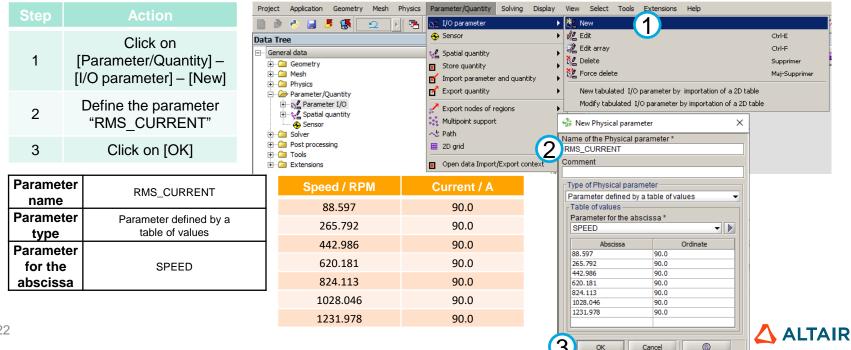




- Flux 2D project: physics modification
 - Create physics parameters: GAMMA

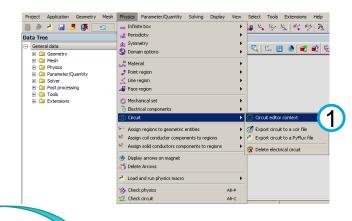


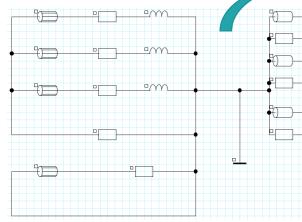
- Flux 2D project: physics modification
 - Create physics parameters: RMS_CURRENT

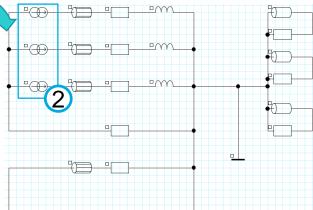


- Flux 2D project: physics modification
 - Modify the coupling electric circuit

Step	Action
1	Click on [Physics] - [Circuit] - [Circuit editor context]
2	Add three current sources to the coupling electric circuit





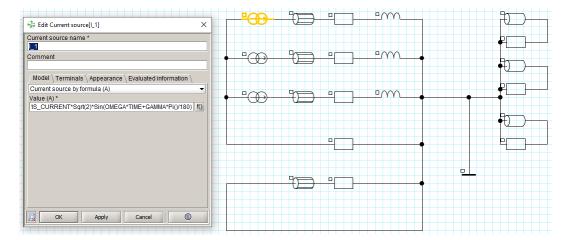




- Flux 2D project: physics modification
 - Modify current values

Step	Action
1	Double click on each current sources, and modify the current value

Parameter name	Value
I_1	RMS_CURRENT*Sqrt(2)*Sin(OMEGA* TIME+GAMMA*Pi()/180)
I_2	RMS_CURRENT*Sqrt(2)*Sin(OMEGA* TIME+GAMMA*Pi()/180-2*Pi()/3)
I_3	RMS_CURRENT*Sqrt(2)*Sin(OMEGA* TIME+GAMMA*Pi()/180-4*Pi()/3)

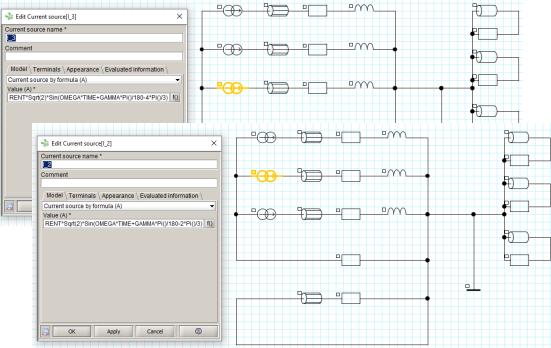




- Flux 2D project: physics modification
 - Modify current values

Step	Action
1	Double click on each current sources, and modify the current value

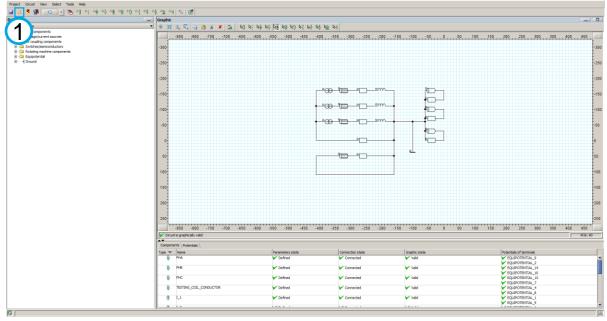
Parameter name	Value
I_1	RMS_CURRENT*Sqrt(2)*Sin(OMEGA* TIME+GAMMA*Pi()/180)
I_2	RMS_CURRENT*Sqrt(2)*Sin(OMEGA* TIME+GAMMA*Pi()/180-2*Pi()/3)
I_3	RMS_CURRENT*Sqrt(2)*Sin(OMEGA* TIME+GAMMA*Pi()/180-4*Pi()/3)





- Flux 2D project: physics modification
 - Close the electric circuit editor

Step	Action
1	Click on the icon to exit the circuit editor context

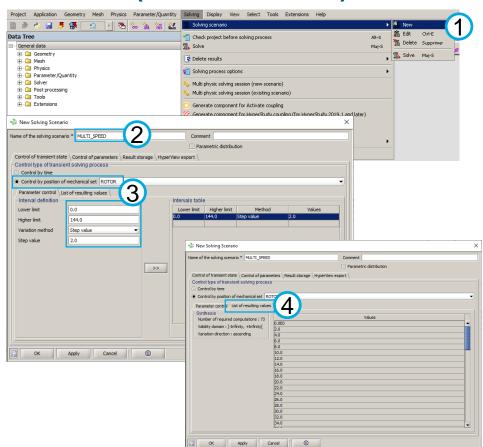




- Flux 2D project: solving
 - Create solving scenario

Step	Action
1	Click on [Solving] – [Solving scenario] – [New]
2	Define the solving scenario "MULTI_SPEED"
3	Define the first control parameter "ROTOR"
4	Click on "List of resulting values" to verify the values

Parameter name	ROTOR
Lower limit	0.0
Higher limit	144.0
Variation method	Step value
Step value	2.0

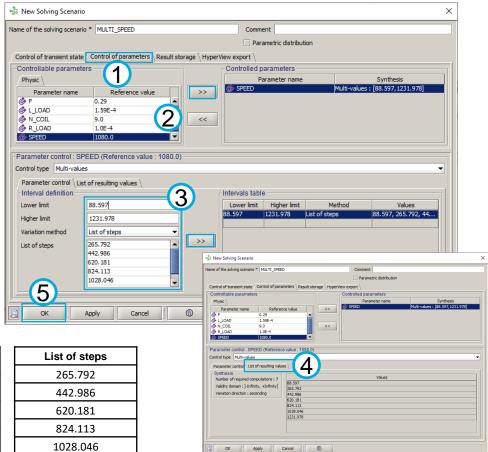




- Flux 2D project: solving
 - Create solving scenario

Step	Action
1	Click on [Control of parameters]
2	Select the physic parameter "SPEED", and click on [>>]
3	Define the second control parameter "SPEED", and click on [>>]
4	Click on "List of resulting values" to verify the values
5	Click on [OK]

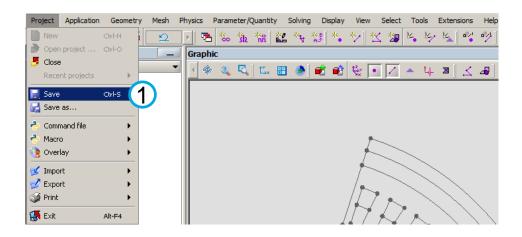
Parameter name	SPEED
Lower limit	88.597
Higher limit	1231.978
Variation method	List of steps





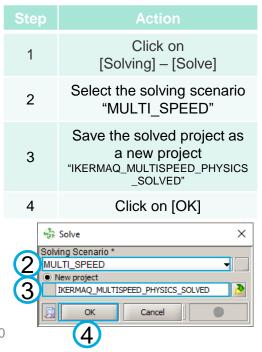
- Flux 2D project: solving
 - Save the project

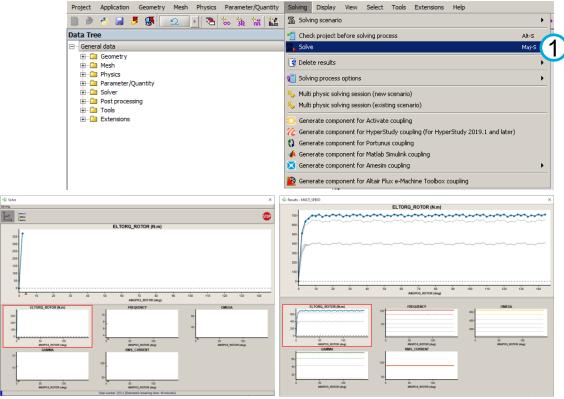
Step	Action
1	Click on [Project] – [Save]





- Flux 2D project: solving
 - Solve the project

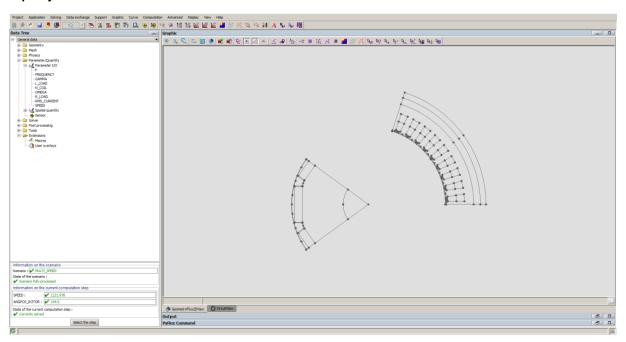






Computation time: 40 min

- Flux 2D project: solving
 - Solve the project



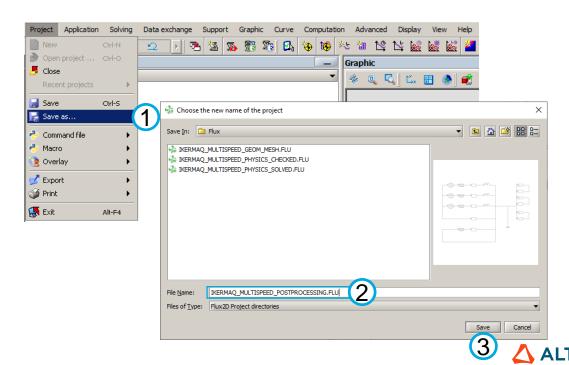


MAGNETIC FORCE EXPORT (NODAL FORCES AND GLOBAL FORCES)



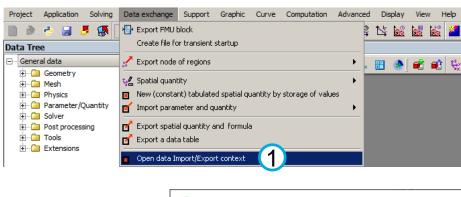
- Flux 2D project: post-processing
 - Save the project

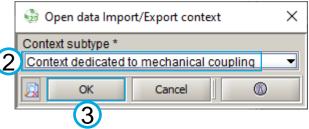
Step	Action
1	Click on [Project] – [Save as]
2	Define the name as "IKERMAQ_MULTISPEED_ POSTPROCESSING.FLU"
3	Click on [Save]



- Flux 2D project: post-processing
 - Open data import / export context

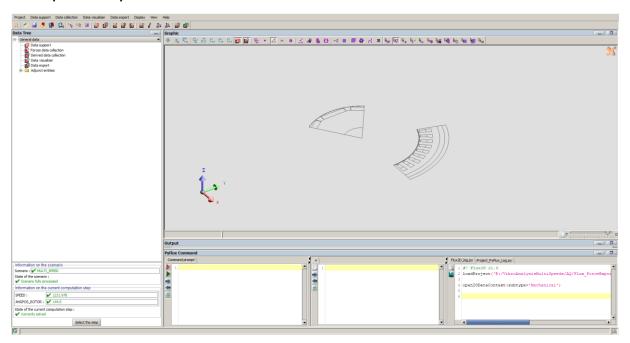
Step	Action
1	Click on [Data exchange] – [Open data Import / Export context]
2	Select the [Context dedicated to mechanical coupling]
3	Click on [OK]







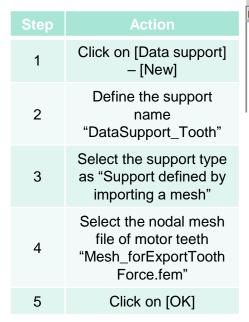
- Flux 2D project: post-processing
 - Open data import / export context

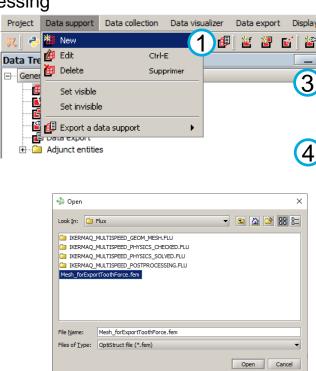


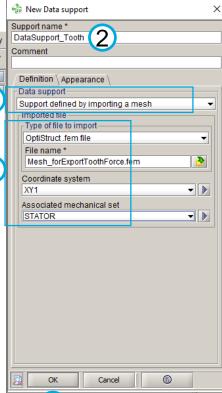


Flux 2D project: post-processing

Create data support



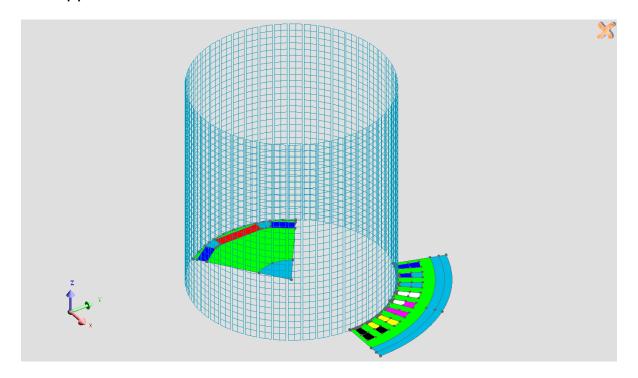








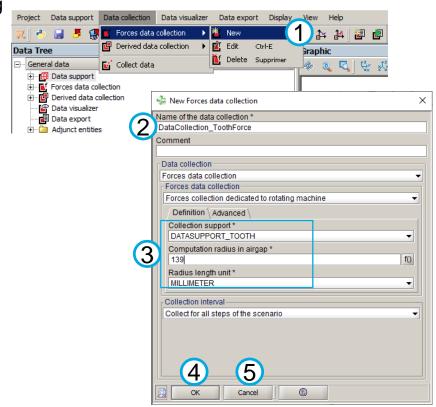
- Flux 2D project: post-processing
 - Create data support





- Flux 2D project: post-processing
 - Create force data collection

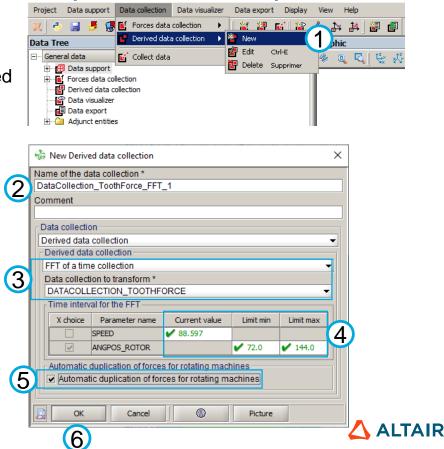
Step	Action
1	Click on [Data collection] – [Forces data collection] – [New]
2	Define the force data collection name "DataCollection_Tooth Force"
3	Define the data support and the computation radius as 139 mm
4	Click on [OK]
5	Click on [Cancel]





- Flux 2D project: post-processing
 - Create derived data collection for each speed

Step	Action
1	Click on [Data collection] – [Derived data collection] – [New]
2	Define the support name "DataCollection_ToothForce_ FFT_1"
3	Define the data collection
4	Select the speed value and the ANGLE interval [72, 144]
5	Click on the "Automatic duplication of forces for rotating machines"
6	Click on [OK]

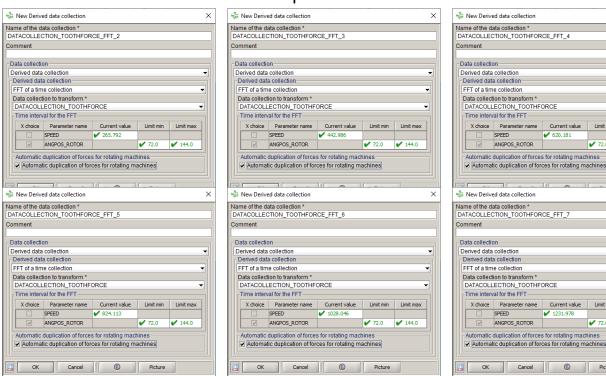


√ 72.0

√ 72.0

144.0

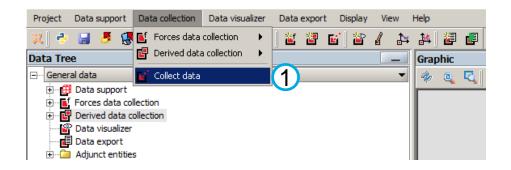
- Flux 2D project: post-processing
 - Create derived data collection for each speed





- Flux 2D project: post-processing
 - Collect data

Step	Action
1	Click on [Data collection] – [Collect Data]

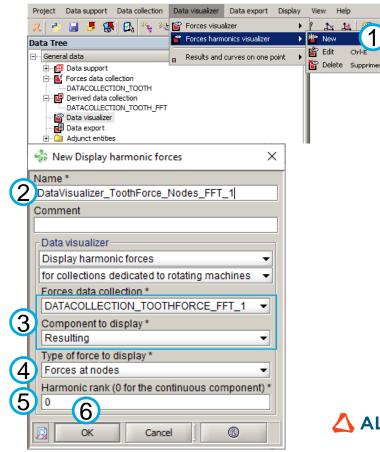


Execution time: 10 min



- Flux 2D project: post-processing
 - Create data visualizer for each speed
 - Nodal forces

Step	Action
1	Click on [Data visualizer] – [Forces harmonics visualizer] – [New]
2	Define the visualizer name "DataVisualizer_ToothForce_ Nodes_FFT_X"
3	Select the objective speed and the component as "Resulting"
4	Select the type as "Forces at nodes"
5	Select the rank as 0
6	Click on [OK]

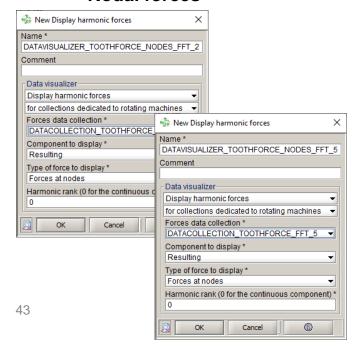


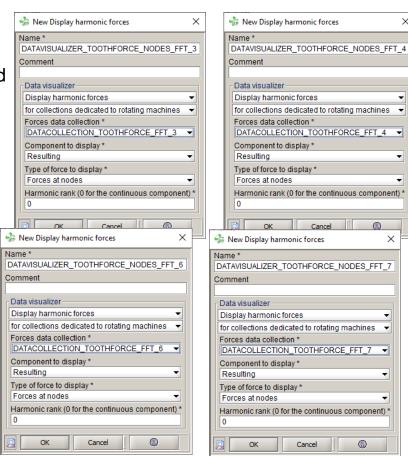


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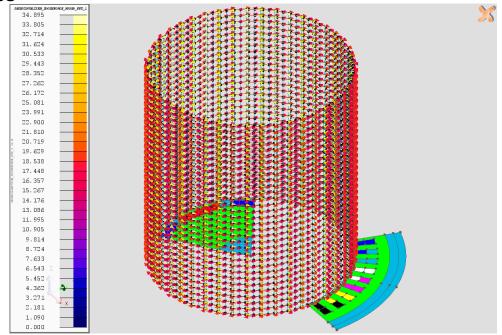
- Flux 2D project: post-processing
 - Create data visualizer for each speed
 - Nodal forces







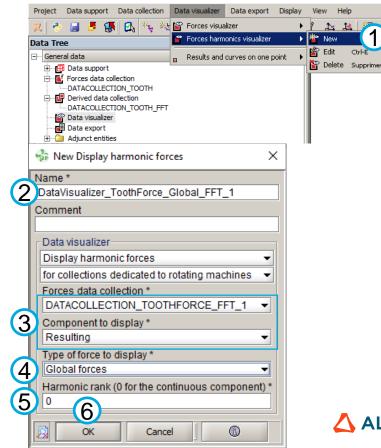
- Flux 2D project: post-processing
 - Create data visualizer for each speed
 - Nodal forces





- Flux 2D project: post-processing
 - Create data visualizer for each speed
 - Global forces

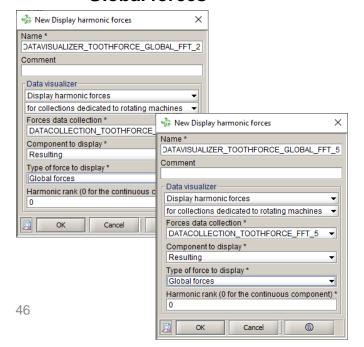
Step	Action
1	Click on [Data visualizer] – [Forces harmonics visualizer] – [New]
2	Define the visualizer name "DataVisualizer_ToothForce_ Global_FFT_X"
3	Select the objective speed and the component as "Resulting"
4	Select the type as "Global forces"
5	Select the rank as 0
6	Click on [OK]

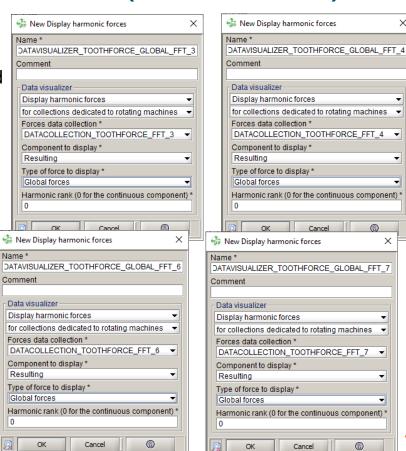




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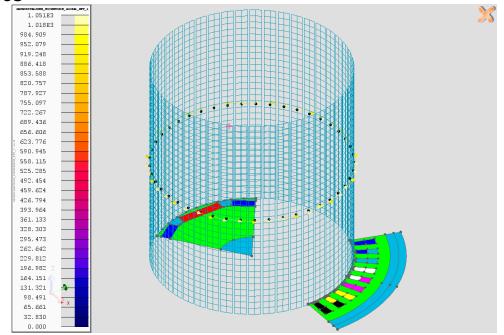
- Flux 2D project: post-processing
 - Create data visualizer for each speed
 - Global forces







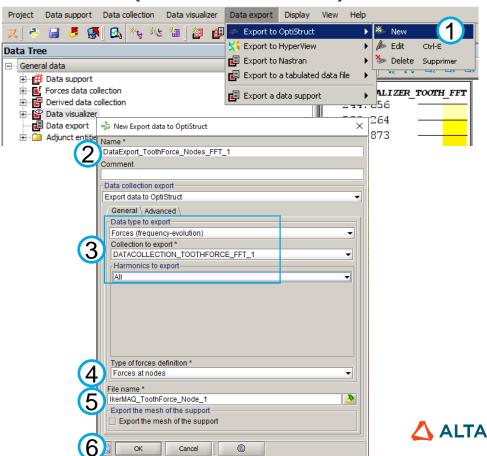
- Flux 2D project: post-processing
 - Create data visualizer for each speed
 - Global forces





- Flux 2D project: post-processing
 - Create data export for each speed
 - Nodal forces

Step	Action
1	Click on [Data export] – [Export to OptiStruct] – [New]
2	Define the data export name "DataExport_ToothForce_Nod es_FFT_X"
3	Define the data type and the collection
4	Select the type as "Forces at nodes"
5	Define the export file name "IkerMAQ_ToothForce_Node_X"
6	Click on [OK]





🖟 New Export data to OptiStruct

- Data collection export

Export data to OptiStruct

General Advanced

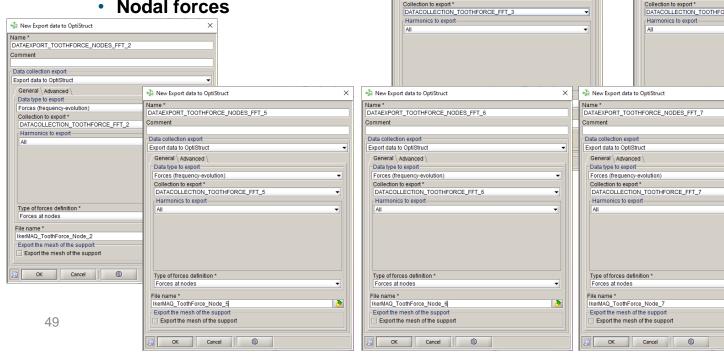
Forces (frequency-evolution)

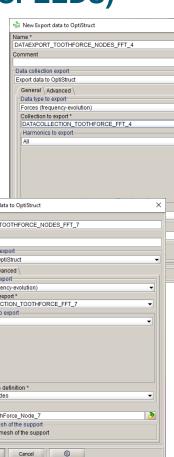
Data type to export

DATAEXPORT_TOOTHFORCE_NODES_FFT_3

- Flux 2D project: post-processing
 - Create data export for each speed





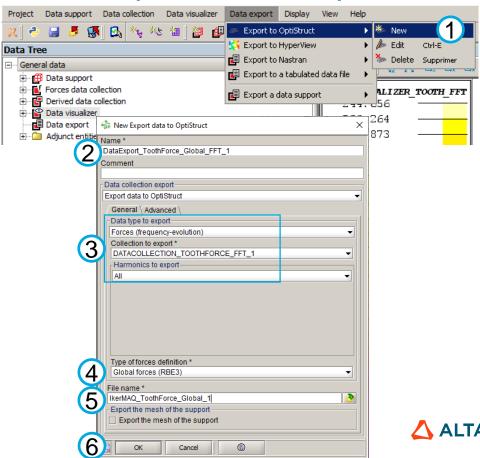




- Flux 2D project: post-processing
 - Create data export for each speed
 - Global forces

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Step	Action
1	Click on [Data export] – [Export to OptiStruct] – [New]
2	Define the data export name "DataExport_ToothForce_Global _FFT_X"
3	Define the data type and the collection
4	Select the type as "Global forces (RBE3)"
5	Define the export file name "IkerMAQ_ToothForce_Global_X"
6	Click on [OK]





🖟 New Export data to OptiStruct

- Data collection export

Export data to OptiStruct

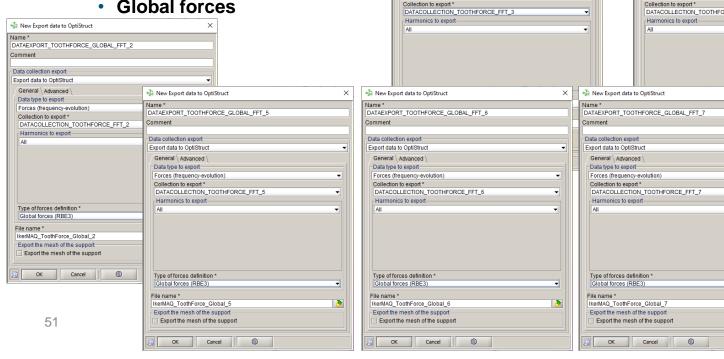
General Advanced

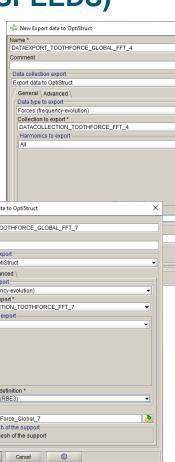
Forces (frequency-evolution)

Data type to export-

DATAEXPORT_TOOTHFORCE_GLOBAL_FFT_3

- Flux 2D project: post-processing
 - Create data export for each speed
 - Global forces

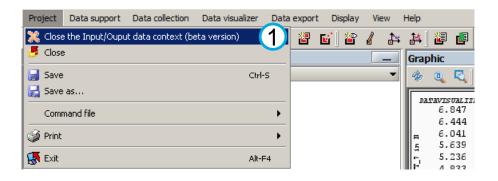






- Flux 2D project: post-processing
 - Close the I/O context

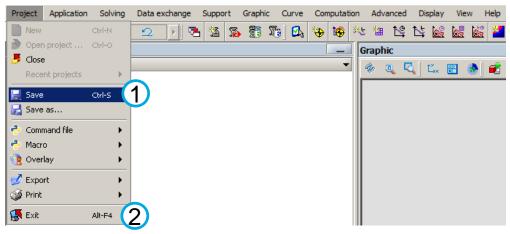
Step	Action
1	Click on [Project] – [Close the Input/Output data context]





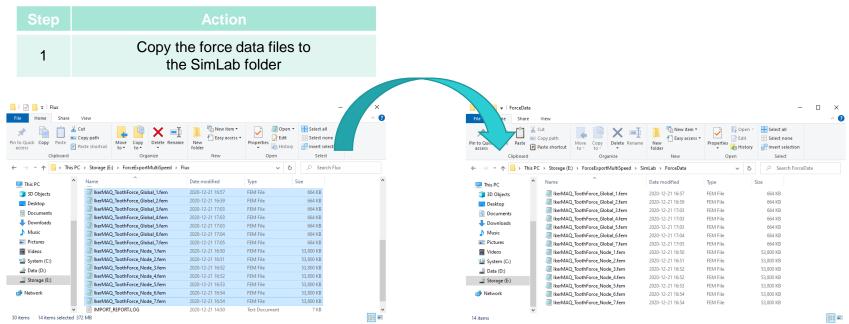
- Flux 2D project: post-processing
 - Close the project







- Flux 2D project: post-processing
 - Export the force per tooth

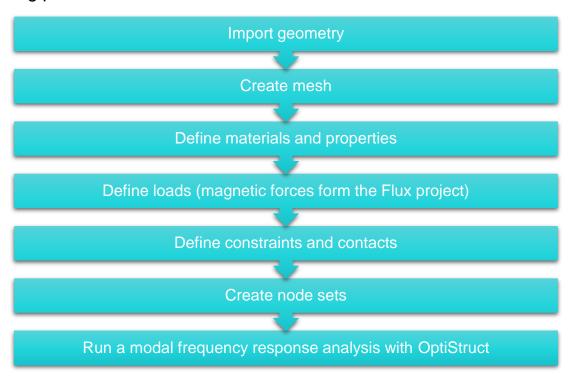




IV. VIBRATION ANALYSIS IN SIMLAB



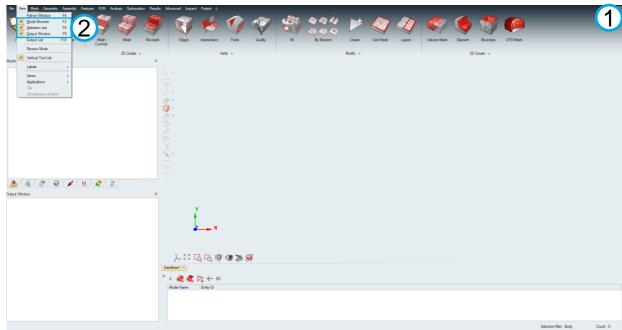
SimLab modeling process





- SimLab project: initiation
 - Windows view configuration

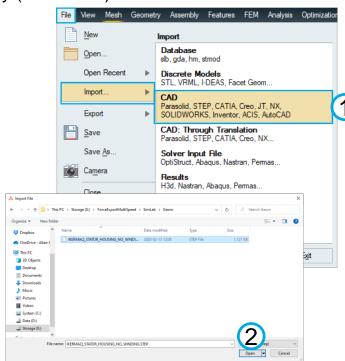
Step	Action
1	Open the software SimLab
2	Click on [View], select "Model Browser", "Selection List" and "Output Window"

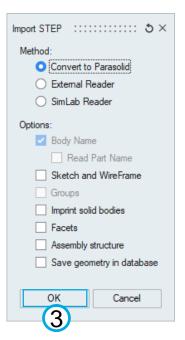




- SimLab project: initiation
 - Import motor geometry (.STEP file)

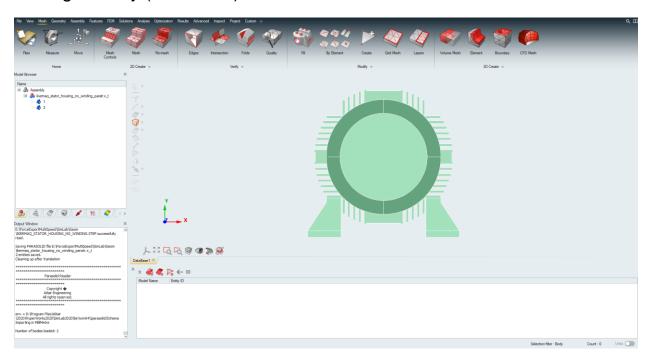
Step	Action
1	Click on [File] – [Import] – [CAD]
2	Select the file "IKERMAQ_STATOR_HOU SING_NO_WINDING.STEP" in the folder "~/ForceExportMultiSpeed /SimLab/Geom", click on [Open]
3	Verify the import setting, and click on [OK]







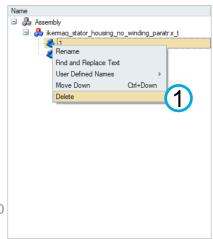
- SimLab project: initiation
 - Import motor geometry (.STEP file)

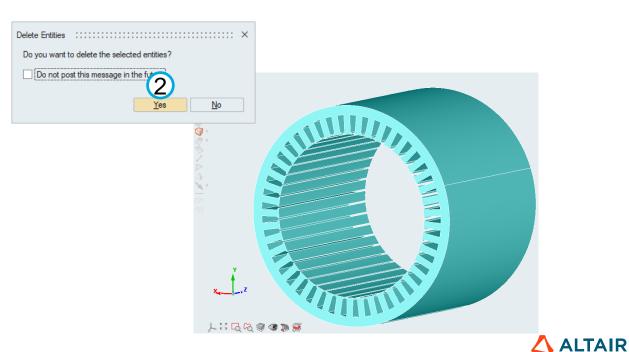




- SimLab project: initiation
 - Motor geometry modification

Step	Action
1	Right click on the component "1", and click on [Delete]
2	Click on [Yes]



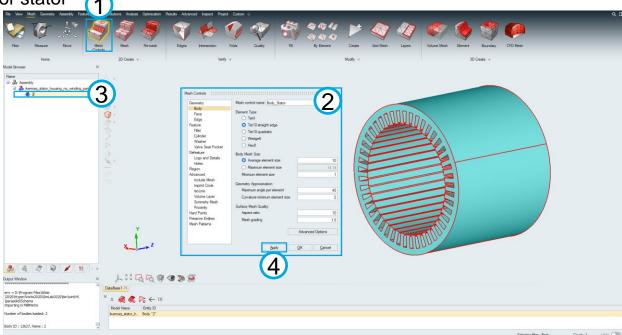


SimLab project: meshing

Create Mesh Control for stator

Step	Action
1	In the [Mesh] ribbon, click on [Mesh Control] icon
2	Define the mesh control parameters
3	Select the body stator
4	Click on [OK]

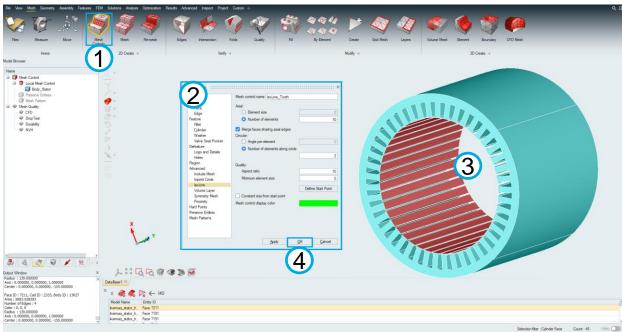
Name	Body_Stator
Туре	Body
Element type	Tet 10 straight edge
Body mesh size	Average element size: 10





- SimLab project: meshing
 - Create Mesh Control for tooth face

Step	Action
1	In the [Mesh] ribbon, click on [Mesh Control] icon
2	Define the mesh control parameters
3	Select all the 45 tooth faces
4	Click on [OK]
Name	IsoLine_Tooth
Туре	IsoLine
Element si	ze 10
Number of elements along circ	2

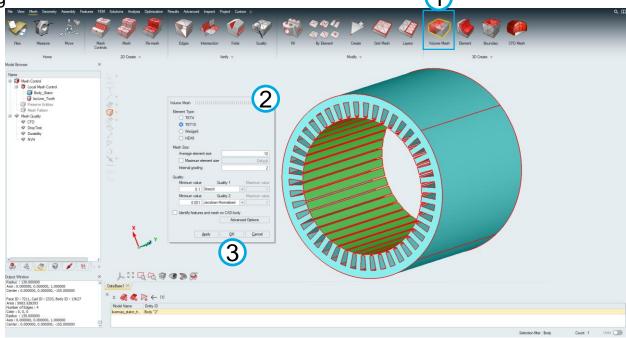




SimLab project: meshing

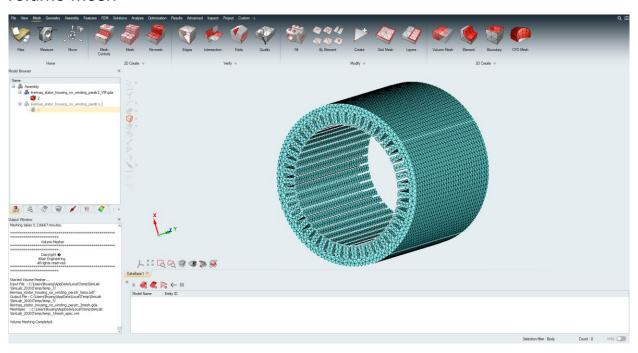
· Create volume mesh

Step	Action
1	In the [Mesh] ribbon, click on [Volume Mesh] icon
2	Verify the volume mesh parameters
3	Click on [OK]



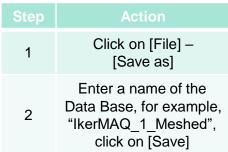


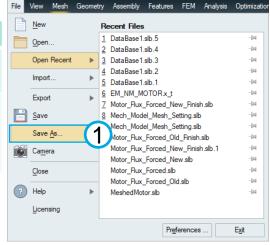
- SimLab project: meshing
 - Create volume mesh

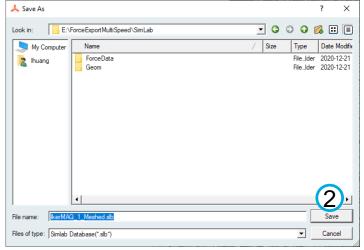




- · SimLab project: meshing
 - Save the Data Base



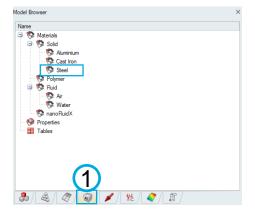


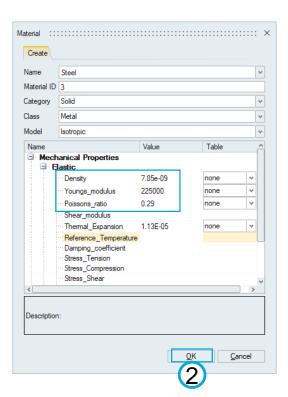




- SimLab project: material update
 - Update predefined material properties

Step	Action
1	Click on the [Property] tab of the Model Browser
2	Double click on the material "Steel", update the material properties.



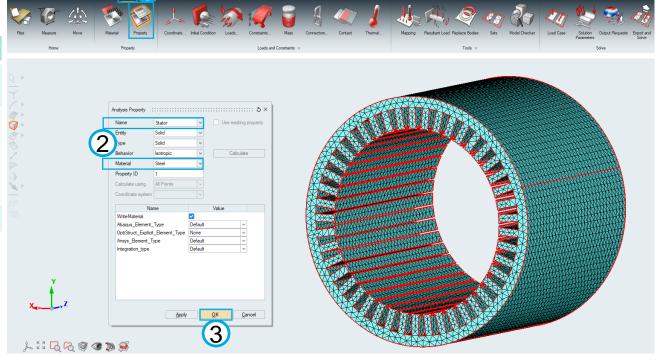




SimLab project: property

STATOR

Step	Action
1	In the [Analysis] ribbon, click on [Property] icon
2	Create the Property "Stator", select the material as "Steel", and assign to the "STATOR" region.
3	Click on [OK]

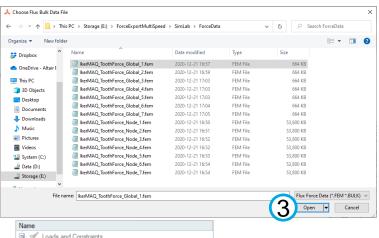




- SimLab project: magnetic force definition
 - · Import magnetic force data

Step	Action
1	In [Model Browser], click on the [Loads and Constraints] tab
2	Right click on the [Loads and Constraints] and click on [Import Flux Bulk Data]
3	Select one of the force data files in the folder ~\ForceExportMultiSpeed\ SimLab\ForceData, and click on [Open]



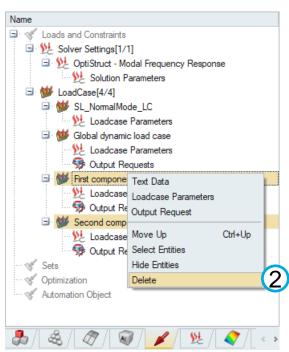






- SimLab project: magnetic force definition
 - · Delete other load cases

Step	Action
1	Select the following two load cases¹: - First component dynamic load case - Second component dynamic load case
2	Right click and click on [Delete]

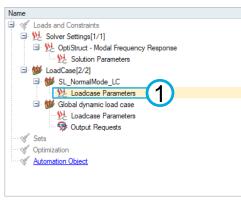


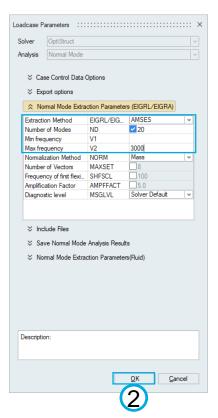


¹ if the force file is generated by Flux 2020, there will be a third component, which is also to be deleted.

- SimLab project: magnetic force definition
 - Modify load setting: SL_NormalMode_LC

Step	Action
1	Double click on the load case "Loadcase Parameters" for the first LoadCase
2	Modify the setting in the "Normal Mode Extraction Parameters (EIGRL/EIGRA)", and click on OK

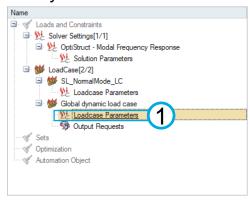


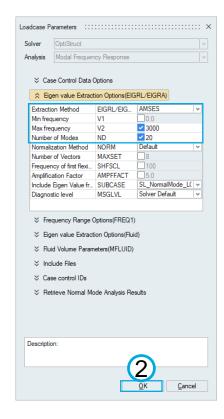




- SimLab project: magnetic force definition
 - · Modify load setting: Global dynamic load case

Step	Action
1	Double click on the load case "Loadcase Parameters" for the second LoadCase
2	Modify the setting in the "Normal Mode Extraction Parameters (EIGRL/EIGRA)", and click on OK

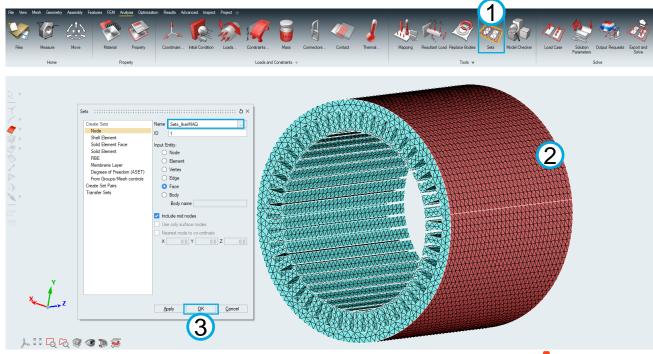






- SimLab project: node set
 - Define node set

Step	Action
1	In the [Analysis] ribbon, click on icon [Sets]
2	Select all the outer faces of the Stator body.
3	Define the name of the sets and click on [OK]

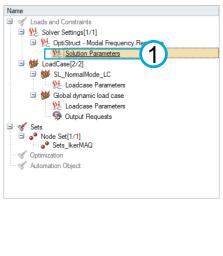


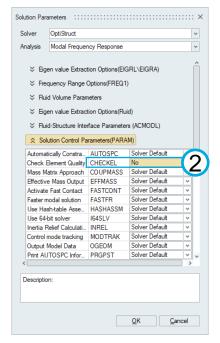


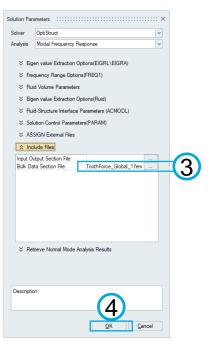
SimLab project: solver setting

Define solver settings

Step	Action
1	In the [Loads and Constraints] tab, double click on the [Solution Parameters]
2	Select "No" for the option "Check Element Quality" in the "Solution Control Parameters" tab
3	Verify the force information (Bulk Data) in the "Include Files" tab
4	Click on [OK]





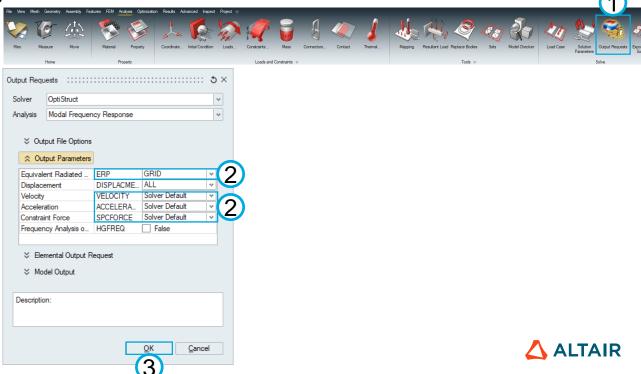




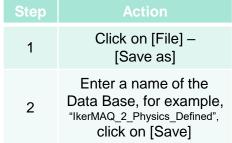
SimLab project: solver setting

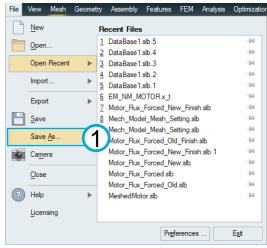
Define output requests

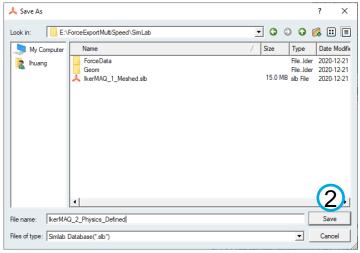
Step	Action
1	In the [Analysis] ribbon, click on the icon [Output Requests]
2	In the [Output Parameters] tab, modify the setting for different parameters
3	Click on [OK]



- SimLab project: export and solve
 - · Save the Data Base

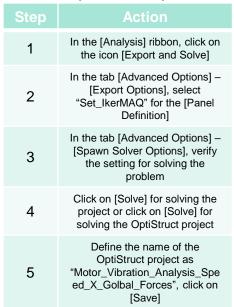


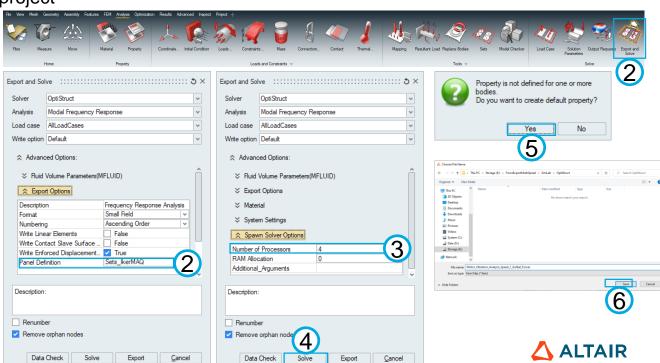






- SimLab project: export and solve
 - Export the OptiStruct project





Result visualization

Step	Action
1	Open the generated .mvw file

☐ | ☑ ☐ 〒 | OptiStruct

Pin to Quick Copy Paste

Clipboard

hwsolver.mesq

access

This PC

3D Objects

Documents

Downloads

Desktop

Music

Pictures

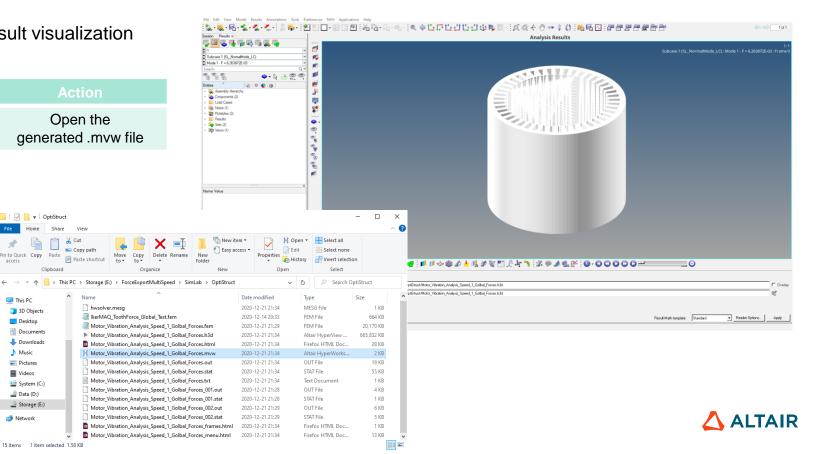
Videos

System (C:)

Network

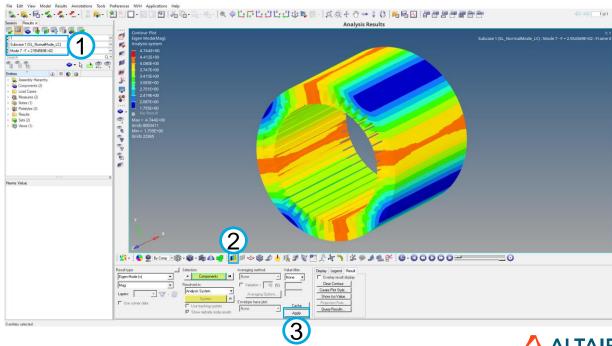
A Storage (E:)

15 items 1 item selected 1,58 KB



- Result visualization
 - Eigen modes

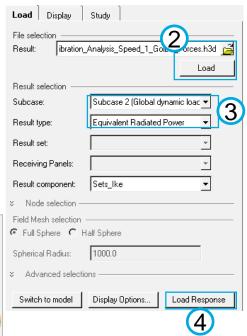
Step	Action
1	Select the [Subcase 1], and select the mode to be visualized
2	Click on the icon 🗾
3	Click on [Apply]

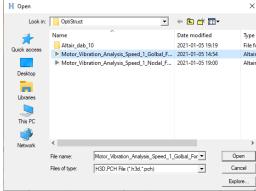


- Result visualization
 - ERP (equivalent radiated power) curve

Step	Action
1	Click on [NVH] – [Radiated Sound]
2	Click on the icon to open the result file, and click on [Load]
3	Select [Subcase 2]
4	Click on [Load Response]

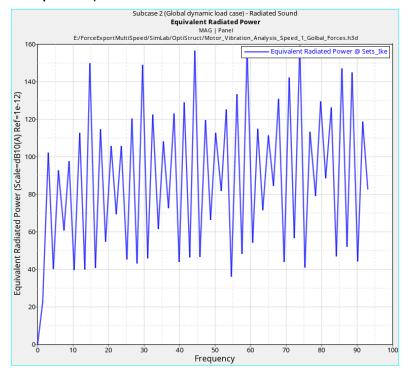








- Result visualization
 - ERP (equivalent radiated power) curve





V. CONCLUSION



CONCLUSION

- Altair HyperWorks provide a convenient analysis process for the vibration problem of electric motors.
- Flux is used as the solver for electromagnetic problems.
- Magnetic forces at multispeed point are computed in the mechanical I/O context in Flux.
- OptiStruct is used as the solver for mechanical problems.
- SimLab is used for modeling the device.



THANK YOU

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